OFFLINE COMPUTING AND SOFTWARE MANUAL [GM2 V5_00_00]

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What is this document?

This document is meant to be a user's manual to the Muon g-2 offline and simulation software and computing system. This document is a PDF file, so it is trivial to search and you can copy it to your computer/tablet/phone/watch and read it anywhere. It is also generated by a git repository using the same build system infrastructure as our code base, so it is easy to version itself and keep in sync with code versions. We also support writing sections directly in LaTeX (which you probably already know) and in Markdown (like LaTeX, but simpler). Finally, there's a special script that can run shell commands and put the output directly in the document (no cutting and pasting).

The idea is to have documentation that is easy to read, easy to write, and easy to keep up to date. All links in the document are clickable in your PDF reader.

One nice thing about having Wiki pages was that each page can be short and so the documentation looks manageable, until you try to find something. The problem with one big PDF file is that it will be big and will look overwhelming. Remember to read the section titles carefully and just read what you need. Furthermore, all of the links to sections (e.g. in the table of contents) are live and will allow you to navigate the file easily. Nearly every PDF reader has a back button to take you back to previously read pages (back-traversing links if necessary); it will probably come in handy.

1.1 What code goes with this document?

The title of this document states the corresponding version of gm2. gm2 is the "umbrella" product that specifies a release. For example, this version of the document goes with gm2 v5_00_00. On the bottom of the title page is the git version information for this document itself. For this version, it reads v5_00_00_01-0-g0be91c0-dirty. There are three or four parts to this description, separated by dashes

¹ This document replaces the documentation we had in the Redmine Wiki because the Wiki was hard to edit and keep up-to-date, hard to sync with versions, hard to search, and required a network connection.

(not underscores; the underscores are part of the version). The first part corresponds to the gm2 version, with an additional two digits at the end since the documentation may be updated more often than the g-2 code. This version should be the git tag of this document. The second part is the number of commits past the tag. If it is non-zero, then there are untagged changes. The third part is g followed by the git hash of the commit corresponding to this document (e.g. Obe91c0). All of this could be followed by -dirty, which means that this document comes from source files with uncommitted changes.²

1.2 Obtaining newer versions of this documentation

The latest official version of this documentation is in GM2 DocDB as GM2-DOC-1825.³ If you want look at an old version of the documentation, you can do that in DocDB, or better, build the specific version you want, as described in the next section.

1.3 Obtaining the source for this documentation, contributing to it, and building it

To get the source,⁴ follow the instructions in section 3. When you get to section 3.3, instead of checking out gm2artexamples, checkout gm2swdocs. You will be in the develop branch. If you want to checkout a particular tag, branch, or hash, you can do that with the git checkout command. For example,

```
git tag  # Show all of the tags
git checkout v5_00_00_02  # Check out sources for this tag
```

You can also do git checkout on a git commit hash value to checkout the sources for that particular commit.

You can build those sources into the pdf file by doing . mrb s and then mrb b. The resulting pdf file will be at \$MRB_BUILDDIR/gm2swdocs/latex/manual.pdf.

1.3.1 Changing and adding to documentation

If you want to change or add documentation, you should start a feature branch with git flow feature start <your_branch_name>. You can then alter or add your own documentation. When you are ready to complete your feature branch, send mail to gm2-sim@fnal.gov and let people look at your changes first.

There are several directories in gm2swdocs. You should not need to alter anything in the Modules nor ups directories. The former contains cmake macros needed for building the source files into PDF. The

- ² Official documentation has zero for the second part and no -dirty.
- ³ DocDB uses its own versioning scheme (just a sequential number) which does not correspond to the gm2 release.
- ⁴ Note: The program pandoc at http://johnmacfarlane.net/pandoc is used to convert markdown and other file formats to LaTeX. pandoc will soon be part of our gm2 release, but in the meantime, you can download it for your Mac by clicking on the previous link. You can also download it for Linux, but it will be easier if you wait for it to be in the release.

latter is for the build and release system. The other directories, latex, markdown, bashmd is where you'll put your documentation or make changes.

The latex directory has files in LaTeX as well as some LaTeX infrastructure files. The most important file in there is manual.tex, which is the main driver file for this document.⁵ All other parts come in with an \include{filename.tex} command. You should not alter manual.tex except to add a \include for your document file. If you add your own LaTeX file in the latex directory, you must add the corresponding \include to manual.tex, and follow instructions in latex/CMakeLists.txt.

The markdown directory has files written in the Markdown format and converted by Pandoc. A Google search on Markdown will give you lots of information. The Pandoc variant of Markdown is described in http://johnmacfarlane.net/pandoc/demo/example9/ pandocs-markdown.html. See existing files in this directory for examples. If you want to write something quickly and do not need fancy La-TeX, then Markdown is the way to go. If you add a file to this directory, you must follow the instructions in markdown\CMakeLists.txt.

The bashmd directory has files written in Markdown but also actually runs bash code with the output going into the document. The best file to look at for an example is bashmd/gettingStarted_gm2artexamples.bashmd. Again, if you add a file to this directory, see bashmd/CMakeLists.txt for instructions.

Pandoc understands many Wiki mark-up formats. If you have a favorite one, it is possible to add it to this document and have pandoc process it. Ask for help. If you are not passionate about mark-up formats, then please just use Markdown as it works very well.

Building the documentation 1.3.2

Assuming your environment is set up (see above) then you need to do, once per session, . mrb s . Then you can do mrb b to build everything. The first time will be slow since you have to run all the commands in bashmd/gettingStarted_gm2artexamples.bashmd. But subsequent builds will be quite fast. Note that pdflatex will run many times to ensure that references and table of contents are all resolved.

The output PDF file will be in \$MRB_BUILDDIR/gm2swdocs/latex/manual.pdf. On a Mac, you can view it with,

open \$MRB_BUILDDIR/gm2swdocs/latex/manual.pdf

When you have completed your feature branch, send mail to gm2-sim@fnal.gov and await further instructions.

⁵ We are using a document class based on "Tufte" documents, where notes go into the wide right margin. Please see the existing LaTeX files for examples.

$Releases\ of\ gm2$

This sections describes the various releases of gm2.

Note the new version numbering scheme. The plan is that new versions of art advance the first number. New versions of g-2 code advance the second number. Bug fixes for g-2 code advance the last number. This release is the fifth one for g-2 since time began, thus the v5.

 $gm2 v5_00_0 has the following:$

- art v1_12_02 Release Notes
- root v5_34_21b
- geant4 v4_9_6_p03e
- gcc v4_9_1 with -std=c++1y for C++14 features.

More needs to go here.

2.2 gm2 v201402 -q e4:prof

gm2 v201402 has the following: More needs to go here.

Getting started with gm2artexamples

This section is a short tutorial to show you quickly how to get started by,

- Logging in and selecting a release (the latest)
- Starting a development area
- Checking out code (gm2artexamples)
- Building it
- Testing
- Running
- · Logging in again

For this tutorial, we'll use the gm2artexamples product. This is a good product to use if you are getting started.

3.1 Logging in and selecting a release area

Fermilab has several interactive virtual machines for use by the Muon g-2 collaboration. See here for more information about how to log in. Our releases (libraries, executables) are served by CVMFS.² CVMFS is already mounted on the Fermilab interactive VMs. If you have a Mac, you can install CVMFS yourself by looking here, and then use your Mac to develop code.

Once you've logged into the machine, you need to select a release area. You *always*³ need to do this step everytime you log in. If you are on a Fermilab interactive VM (gm2gpvm01, gm2gpvm02, gm2gpvm03, gm2gpvm04), you select the release area by doing,

\$ source /grid/fermiapp/gm2/setup # On qm2qpvm machine

Note that \$ is the shell prompt (don't type it in).

If you are on a Mac or another system with CVMFS OASIS installed, you do (and will see in response, which will be the same as the command above)

- ¹ We use the terms product, project, and package somewhat interchangeably. All of our products live on the Redmine server, http://redmine.fnal.gov
- 2 CVMFS is a system that serves application code and updates automatically when new files are released.
- ³ You need to do this step everytime you log in because you can use different release areas for the same development area, say, for example, if CVMFS is down or you are sharing a directory between your Mac and a Linux system.

\$ source /cvmfs/oasis.opensciencegrid.org/gm2/prod/g-2/setup # On Mac

g-2 software --> To list gm2 releases, type ups list -aK+ gm2 --> To use the latest release, do setup gm2 v5_00_00 -q e6:prof

For more information, see https://cdcvs.fnal.gov/redmine/projects/g-2/wiki/ReleaseInformation

You may want to put that source command in your ~/.profile file. Furthermore, if you are on a gm2gpvm machine, you should also put setup git at the bottom of your ~/.profile.

Starting a development area

Now that the release area is selected, you need to make a development area. The development area contains source code, build products, and a personal release area. You typically use a development area for a particular topic, such as adding a feature to the simulation or generating a plot for some study. You can have as many development areas as you want, but only one can be active at a time.

Make an empty directory and go there. If you are on a gm2gpvm machine, you should make an area in /gm2/app/users/<YOUR_NAME>.4 You can put code in your home directory, but that has a small quota and you can easily use it all up. There is no quota on /gm2/app, but it is not backed up.

```
$ mkdir /gm2/app/users/lyon/first-try # On gm2gpvm
$ cd /gm2/app/users/lyon/first-try
```

If you are on your Mac, or some other machine, make the directory where you have room.

```
$ mkdir ~/Development/g-2/first-try # On Mac
$ cd ~/Development/g-2/first-try
```

Since you are starting out with a new area, you must choose a release. You should generally choose the latest, which will be specified in the output when you selected the release area. Just do what the command says.⁵

```
$ setup gm2 v5_00_00 -q e6:prof
```

So here we are setting up g-2 release v5_00_00 with the e6:prof qualifier. e6 indicates the type of compiler we're using (in our case gcc 4.9.1 with C++14 features turned on - this code is decided by the art team) and prof means we'll do a profile build. Profile builds

⁴ If this directory does not exist, you can make it with the mkdir command.

⁵ setup is a *ups* command. UPS is our release and product management system.

are optimized and have debugging symbols turned on. We only use profile builds.

Now, you must create the development area. You will start using the mrb commands. mrb means "multi-repository build system" and is a build system used by Muon g-2, the art developers, and LBNF. You can get a list of mrb commands with (you don't have to type in the full path that you see below),

\$ mrb -h

Usage /cvmfs/oasis.opensciencegrid.org/gm2/prod/external/mrb/v1_03_00_gm2/bin/mrb [-h for help]"

```
Tools (for help on tool, do "/cvmfs/oasis.opensciencegrid.org/gm2/prod/external/mrb/v1_03_00_gm2/bin/mrb <tool> -h" )
 newDev (n)
                              Start a new development area
 gitCheckout (g)
                              Clone a git repository
  svnCheckout (svn)
                              Checkout from a svn repository
  setEnv (s)
                              Setup development environment (mrbSetEnv)
 build (b)
                             Run buildtool
  install (i)
                             Run buildtool with install
  test (t)
                              Run buildtool with tests
  setup_local_products (slp) Setup local products (mrbslp) [not local sources]
  zapBuild (z)
                             Delete everything in your build area
  newProduct (p)
                             Create a new product from scratch
  changelog (c)
                             Display a changelog for a package
  bumpVersion (bv)
                              Bump version number of a package
  updateDeps (ud)
                             Update dependencies in CMakeLists.txt and product_deps
  updateCM (uc)
                             Update the master CMakeLists.txt file
 makeDeps (md)
                              Build or update a header level dependency list
  checkDeps (cd)
                              Check for missing build packages
  pullDeps (pd)
                             Pull missing build packages into MRB_SOURCE
Aliases ( we use aliases for these commands because they must be sourced )
                             Setup a development enviornment and local products [use this more often]
                             (source $MRB_DIR/bin/mrbSetEnv)
```

Setup only the products installed in the working localProducts_XXX directory

The mrb commands are the same if you are on gm2gpvm or your

To initialize your development area, do this in an empty directory.

\$ mrb newDev

mrbslp

```
building development area for gm2 v5_00_00 -q e6:prof
MRB BUILDDIR is /Users/lyon/Development/g-2/first-try/build d13.x86 64
MRB_SOURCE is /Users/lyon/Development/g-2/first-try/srcs
INFO: cannot find releaseDB/base_dependency_database
     mrb checkDeps and pullDeps may not have complete information
MRB_PROEJCT IS gm2
IMPORTANT: You must type
    source /Users/lyon/Development/g-2/first-try/localProducts_gm2_v5_00_00_e6_prof/setup
{\tt NOW} and whenever you log in
```

(source \$MRB_DIR/bin/setup_local_products)

Read the output carefully. Some things to note:

• A build directory is created and note its name contains the flavor of your machine. You can get to that directory easily with cd \$MRB_BUILDDIR .

⁶ Mac is d13 (for Darwin version 13) and slf5, slf6 are marked as appropriate.

- A source directory is created for your source code. You can get to it easily by doing cd \$MRB_SOURCE.
- You can ignore the message about the release database. That's a LBNF thing we don't use.
- The important message is indeed important. There is a set up script that you need to run that sets up your environment. Run that script now and whenever you log in to restore your development environment. You don't need to type in the whole path, since you are at the top of your development area.

\$ source localProducts_gm2_v5_00_00_e6_prof/setup

```
MRB_PROJECT=gm2
MRB_PROJECT_VERSION=v5_00_00
MRB_QUALS=e6:prof
MRB_TOP=/Users/lyon/Development/g-2/first-try
MRB_SOURCE=/Users/lyon/Development/g-2/first-try/srcs
MRB_BUILDDIR=/Users/lyon/Development/g-2/first-try/build_d13.x86_64
MRB_INSTALL=/Users/lyon/Development/g-2/first-try/localProducts_gm2_v5_00_00_e6_prof
```

PRODUCTS=/Users/lyon/Development/g-2/first-try/localProducts_gm2_v5_00_00_e6_prof:/cvmfs/oasis.opensciencegrid.org/gm2/prod/g-2:/cvmfs/oasis.opensciencegrid.org/gm2/prod/g-2:/Users/lyon/Development/g-2/tr

 A local products area is also created. This is your own personal release area that overlays the official one (so stuff you have in your personal release area override products in the official one).

3.3 Checkout code

Now you need to checkout some code. For this example, we'll use the gm2artexamples product. All of our code lives in git repositories on http://redmine.fnal.gov . The mrb gitcheckout command is used to clone the git repositories (this is a convenience command so you don't have to remember the git URLs and other set up tasks). Let's check out the gm2artexamples product. You must be in the srcs directory of your development area. The command is rather chatty.

⁷ You can type mrb g for short.

```
$ cd srcs
$ mrb g gm2artexamples
\verb|git clone: clone gm2artexamples| at /Users/lyon/Development/g-2/first-try/srcs| \\
NOTICE: You do not have read-write permissions for this repository
--->> DID YOU RUN kinit TO GET A KERBEROS TICKET? <<--
NOTICE: Running git clone http://cdcvs.fnal.gov/projects/gm2artexamples
Cloning into 'gm2artexamples'..
ready to run git flow init for gm2artexamples
Already on 'master'
Your branch is up-to-date with 'origin/master'.
Using default branch names.
Already on 'develop'
Your branch is up-to-date with 'origin/develop'.
Branch develop set up to track remote branch develop from origin.
Already up-to-date.
NOTICE: Adding gm2artexamples to CMakeLists.txt file
NOTICE: You can now 'cd gm2artexamples'
You are now on the develop branch (check with 'git branch')
```

To make a new feature, do 'git flow feature start <featureName>'

At this moment, you need to switch to a particular feature branch that is compatible with gm2 v5 00 00. Do the following,⁸

⁸ This step will disappear shortly.

```
$ cd gm2artexamples
$ git flow feature track gm2_5
$ cd ..
Switched to a new branch 'feature/gm2_5'
Branch feature/gm2_5 set up to track remote branch feature/gm2_5 from origin.
Summary of actions:
 A new remote tracking branch 'feature/gm2_5' was created
- You are now on branch 'feature/gm2_5'
```

If you have more code to checkout, then run more mrb g commands.

Building code 3.4

Now that your code is checked out, you need to build it. The first step you need to do is to "extend" your environment with any products your build depends upon set up. The way to do this is to do source mrb setEnv. 9 You need source (or . for short) because your shell environment needs to be extended with new environment variables. You need to run this command after you log back into and start developing. If you do not make major changes to your code (you don't introduce new dependencies), then you only need to run the command once before you build.

⁹ There are two shortcuts for source mrb setenv; you can do . mrb s or mrbsetenv (the latter is a bash function that does the source for you).

\$. mrb s

local product directory is /Users/lyon/Development/g-2/first-try/localProducts_gm2_v5_00_00_e6_prof --- this block should be empty -----ERROR: Cannot do unsetup, SETUP_CETPKGSUPPORT is not defined The working build directory is /Users/lyon/Development/g-2/first-try/build_d13.x86_64 The source code directory is /Users/lyon/Development/g-2/first-try/srcs ----- check this block for errors -----

For now, ignore the error about SETUP_CETPKGSUPPORT (it is benign). You should not see any errors between the dashed lines. If you do, then you have some product dependency mismatch (ask for help). Now you can build your code. The build command is mrb build. 10

 $^{10}\,\mathrm{mrb}$ b for short

\$ mrb b

The long output is not shown. Hopefully there will be no compilation errors. If you get some, ask for help.

3.5 *Testing*

gm2artexamples is currently the only product that has unit tests. To try them, just do mrb test. 11

¹¹ mrb t for short. A short build check will occur to ensure that everything is built.

\$ mrb t

```
/Users/lyon/Development/g-2/first-try/build_d13.x86_64 calling buildtool -I /Users/lyon/Development/g-2/first-try/localProducts_gm2_v5_00_00_e6_prof -b -t INFO: Install prefix = /Users/lyon/Development/g-2/first-try/localProducts_gm2_v5_00_00_e6_prof INFO: CETPKG_TYPE = Prof.
 INFO: Stage cmake.
-- Product is gm2artexamples v2_00_00 e6:prof
-- Module path is /cvmfs/oasis.opensciencegrid.org/gm2/prod/external/art/v1_12_02/Modules;/cvmfs/oasis.opensciencegrid.org/gm2/prod/external/cetbuildtools/v4_03_02/Modules
-- set_install_root: PACKAGE_TOP_DIRECTORY is /Users/lyon/Development/g-2/first-try/srcs/gm2artexamples
-- set_install_root: PACKAGE_TOP_DIRECTORY is /Users/lyon/Development/g-2/first-try/srcs/gm2artexamples
-- Building for Darwin did x86.64
-- set_install_root: PACKAGE_TOP_DIRECTORY is /Users/lyon/Development/g-2/first-try/srcs/gm2artexamples
-- Selected diagnostics option CAUTIOUS
-- cmake build type set to Prof in directory <top> and below
-- DEFINE (-D): ;NDEBUG
-- compiler flags for directory <top> and below
-- C++ FLAGS: -03 -g -gdwarf-2 -fno-omit-frame-pointer -Werror -pedantic -std=c++1y -Wall -Werror=return-type
-- C FLAGS: -03 -g -gdwarf-2 -fno-omit-frame-pointer -Werror -pedantic -Wall -Werror=return-type
 -- Boost version: 1.56.0
boost version: 1.55.0
-- Found the following Boost libraries:
-- chrono
-- date_time
             filesystem
graph
iostreams
              locale
              prg_exec_monitor
program_options
               random
               regex
serialization
               signals
               system
               thread
              timer
unit_test_framework
               wave
              wserialization
 -- CPACK_PACKAGE_NAME and CPACK_SYSTEM_NAME are gm2artexamples d13-x86_64-e6-prof
-- Configuring done
CMake Warning (dev):
Policy CMP0042 is not set: MACOSX_RPATH is enabled by default. Run "cmake --help-policy CMP0042" for policy details. Use the cmake_policy command to set the policy and suppress this warning.
      {\tt MACOSX\_RPATH} \  \, {\tt is\  \, not\  \, specified\  \, for\  \, the\  \, following\  \, targets:}
         gm2artexamples_DataObjects_dict
         gm2artexamples_DataObjects_map
gm2artexamples_HitAndTrackObjects_dict
gm2artexamples_HitAndTrackObjects_map
gm2artexamples_Lesson1_HelloWorld1_module
         gm2artexamples_Lesson1_HelloWorld1_module
gm2artexamples_Lesson1_MplatumReader_module
gm2artexamples_Lesson1_MyDatumReader_module
gm2artexamples_Lesson1_ProduceMyLittleDatum_module
gm2artexamples_Lesson2_makeHits_module
gm2artexamples_Lesson2_makeRotatedHits_module
gm2artexamples_Lesson2_makeSimpleTracksFromNewHits_module
gm2artexamples_Lesson2_makeSimpleTracksFromNedHits_module
gm2artexamples_Lesson2_readHits_module
gm2artexamples_Lesson2_readHits_module
gm2artexamples_Lesson2_readHits_module
test_MyLittleDatumAnalyzer_module
test_MyLittleDatumAnalyzer_module
 This warning is for project developers. Use -Wno-dev to suppress it.
  -- Generating done
 -- Build files have been written to: /Users/lvon/Development/g-2/first-trv/build d13.x86 64
 INFO: Stage cmake successful.
 INFO: gm2artexamples version 2.00.00 configured.
                                                   _____
 INFO: Stage build.
[ 3%] Built target gm2artexamples_DataObjects
[ 9%] Built target gm2artexamples_DataObjects_dict
[ 15%] Built target gm2artexamples_DataObjects_dict
[ 15%] Built target gm2artexamples_HitAndTrackObjects
[ 28%] Built target gm2artexamples_HitAndTrackObjects_dict
[ 34%] Built target gm2artexamples_HitAndTrackObjects_map
[ 37%] Built target gm2artexamples_Lesson1,HelloWorld1_module
[ 40%] Built target gm2artexamples_Lesson1_HelloWorld1_module
[ 43%] Built target gm2artexamples_Lesson1_MyDatumReader_module
[ 46%] Built target gm2artexamples_Lesson1_ProduceMyLittleDatum_module
[ 50%] Built target gm2artexamples_Lesson2_makeHits_module
[ 53%] Built target gm2artexamples_Lesson2_makeHits_module
[ 56%] Built target gm2artexamples_Lesson2_makeSimpleTracksFromNewHits_module
[ 56%] Built target gm2artexamples_Lesson2_makeSimpleTracksFromNewHits_module
```

```
[ 62%] Built target gm2artexamples_Lesson2_readHits_module
       [657] Built target gm2artexamples_lesson2_readmits_module
[657] Built target m2artexamples_lesson2_readmits_module
[657] Built target v1sers+1yon+Development+g-2+first-try+build_d13.x86_64+gm2artexamples+bin+wpLittleDatum_wr.sh
[717] Built target +Users+1yon+Development+g-2+first-try+build_d13.x86_64+gm2artexamples+bin+very_simple_test.sh
[757] Built target +Users+1yon+Development+g-2+first-try+build_d13.x86_64+gm2artexamples+test+MyLittleDatum_test.d+MyLittleDatum_test.fcl
[787] Built target +Users+1yon+Development+g-2+first-try+build_d13.x86_64+gm2artexamples+test+MyLittleDatum_test.d+messageDefaults_fcl
[817] Built target +Users+1yon+Development+g-2+first-try+build_d13.x86_64+gm2artexamples+test+MyLittleDatum_vs.sh.d+MyLittleDatum_r.fcl
[847] Built target +Users+1yon+Development+g-2+first-try+build_d13.x86_64+gm2artexamples+test+myLittleDatum_vr.sh.d+MyLittleDatum_vr.fcl
        87%] Built target #Users+Iyon+Development+g-2+first-try+build_d13.x86_64+gm2artexamples+test+myLittleDatum_wr.sh.d+messageDefaults.fcl [90%] Built target simple_test [93%] Built target test_MyLittleDatumAnalyzer_module
          96%] Built target test_MyLittleDatumProducer_module
  [100%] Built target test_with_boost
  real 0m5.019s
  user
                                         0m1.659s
    sys 0m1.361s
  INFO: Stage build successful.
  INFO: Stage test.
| Test project /Users/lyon/Development/g-2/first-try/build_d13.x86_64
| Start 1: very_simple_test.sh | Passed | 0.01 sec |
| Start 2: simple_test | Passed | 0.02 sec |
| Start 2: simple_test | Passed | 0.02 sec |
| Start 3: test_with_boost | Passed | 0.03 sec |
| Start 4: MyLittleDatum_test | Passed | 0.03 sec |
| Start 4: MyLittleDatum_test | Passed | 0.53 sec |
| Start 5: myLittleDatum_wr.sh | Passed | 0.86 sec |
| Start 5: myLittleDatum_wr.sh | Passed | 0.86 sec |
| Start 5: myLittleDatum_wr.sh | Passed | 0.86 sec |
| Start 5: myLittleDatum_wr.sh | Passed | 0.86 sec |
| Start 5: myLittleDatum_wr.sh | Passed | 0.86 sec |
| Start 5: myLittleDatum_wr.sh | Passed | 0.86 sec |
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| Start 5: myLittleDatum_wr.sh | Passed | 0.86 sec |
| Start 5: myLittleDatum_wr.sh | Passed | 0.86 sec |
| Start 5: myLittleDatum_wr.sh | Passed | 0.86 sec |
| Start 5: myLittleDatum_wr.sh | Passed | 0.86 sec |
| Start 5: myLittleDatum_wr.sh | Passed | 0.86 sec |
| Start 5: myLittleDatum_wr.sh | Pass
  100% tests passed, 0 tests failed out of 5
  Total Test time (real) = 1.45 sec
  INFO: Stage test successful.
```

3.6 Running

There are several fcl files you can run for gm2artexamples.

\$ ls \$MRB_SOURCE/gm2artexamples/fcl

```
CMakeLists.txt
hello1.fcl
hello2.fcl
makeAndReadDatum.fcl
makeAndReadTracksFromOldHits.fcl
makeDatum.fcl
makeHits.fcl
makeHitsRotated.fcl
makeTracksFromNewHits.fcl
makeTracksFromOldHits.fcl
messageservice.fcl
minimalMessageService.fcl
readDatum.fcl
readHits.fcl
readSimpleTracks.fcl
```

Our art executable is called gm2. FCL files are found by the \$FHICL_FILE_PATH search path.

\$ gm2 -c hello1.fcl

```
%MSG-i MF_INIT_OK: 19-Nov-2014 02:29:47 CST JobSetup
Messagelogger initialization complete.
Begin processing the 1st record. run: 1 subRun: 0 event: 1 at 19-Nov-2014 02:29:47 CST
```

TimeReport ----- Time Summary ---[sec]---TimeReport CPU = 0.000104 Real = 0.000189

Art has completed and will exit with status 0.

3.7 Logging in again

At some point, you will want to log out of your machine and log back in later to continue your work. To reconstitute your development environment, you need to,

• Select the release area

```
source /grid/fermiapp/gm2/setup # on gm2gpvm
source /cvmfs/oasis.opensciencegrid.org/gm2/prod/g-2/setup # On Mac
```

• Change directory to your development area

```
cd ~/Development/g-2/first-time # On my Mac
```

• Run the setup script in local products (this will re-select the chosen g-2 release)

```
source localProducts_gm2_v5_00_00_e6_prof/setup
```

• Extend the environment for the products your build depends upon (don't forget the leading dot)

```
. mrb s
```

Now you are set to build (mrb b), run (gm2 -c FCL_FILE), and develop.

3.8 Summary

Here is a summary of the commands for $gm2 \ v5_00_0$.

3.8.1 To checkout, build and run gm2artexmples to a new development area

```
# Log into machine (e.g. gm2gpvm.fnal.gov)
```

```
# Select release area
source /grid/fermiapp/gm2/setup # On gm2gpvm
source /cvmfs/oasis.opensciencegrid.org/gm2/prod/g-2/setup # On Mac
# Create development area
mkdir /gm2/app/users/lyon/first-time # For me on gm2gpvm
mkdir ~/Development/g-2/first-time # For me on my Mac
cd <THAT_DIRECTORY>
# Setup the release
setup gm2 v5_00_00 -q e6:prof
# Initialize Development area
mrb newDev
source localProducts_gm2_v5_00_00_e6_prof/setup
# Checkout code
cd srcs
mrb g gm2artexamples
# Get right branch (for now)
cd gm2artexamples
git flow feature track gm2_5
cd ..
# Extend environment with build dependencies
. mrb s
# Build it
mrb b
# Test it
mrb t
# Run it
gm2 -c hello1.fcl
3.8.2 Restoring environment when logging in again later
Here's what you do to restore your environment
# Log into machine (e.g. gm2gpvm.fnal.gov)
# Select release area
source /grid/fermiapp/gm2/setup # On gm2gpvm
```

```
source /cvmfs/oasis.opensciencegrid.org/gm2/prod/g-2/setup # On Mac

# cd to development area
cd /gm2/app/users/lyon/first-time # For me on gm2gpvm
cd ~/Development/g-2/first-time # For me on my Mac

# Restore basic environment
source localProducts_gm2_v5_00_00_e6_prof/setup

# Extend environment with build dependencies
. mrb s

# Now you can work!! For example
mrb b # Build it if you've made a change since last time
mrb t # Test it
gm2 -c hello1.fcl # Run it
```

Running the simulation

This section gives you very brief instructions on how to build and run the gm2ringsim simulation. More details will be coming in future versions of this document.

Be sure you are familiar with the basics in section 3.

At this moment, the released code for the simulation is quite old,¹ so you will have to download and build all the simulation code yourself. The first build will take awhile (about 20 minutes on the gm2gpvm machines), but subsequent builds will be faster.

Set up the gm2 v5_00_00 release and create a new development area. Obtain the source code and switch to the gm2 v5_00_00 branch by following the instructions below.² Perform the following steps in your development area, which we assume is ready to go.

cd srcs

```
# Get artg4
mrb g artg4
cd artg4
git flow feature track gm2_v5
cd ..

# Get gm2geom
mrb g gm2geom
cd gm2geom
git flow feature track g5
cd ..

# Get gm2dataproducts
mrb g gm2dataproducts
cd gm2dataproducts
```

 1 This should be remedied soon as gm2 v5_00_00 is adopted.

² Very soon, the branch switching step will be unnecessary once we adopt gm2 v5_00_00. And unfortunately, I was not consistent with how I named the branches. Sorry.

```
# Get gm2ringsim
mrb g gm2ringsim
cd gm2ringsim
git flow feature track g5
cd ..
```

You can now build the code with,

```
. mrb s
mrb b
```

There are many fcl files that you can use to run the simulation. Here's a list of some of them,

BeamDiagnosticMuPlus.fcl Shoot individual muons that go around the ring with a rudimentary particle gun with the fiber harp deployed.

BeamDiagnosticMuPlusMuonGasGun.fcl Simulation with fiber harp deployed using the gas gun. The gas gun makes muons randomly appear in the ring right before decay. Since geant does not track muons around the ring, this is a very fast simulation.

ProductionMuPlus. fcl Shoot individual muons that go around the ring with the ring in data taking state (e.g. no fiber harp).

ProductionMuPlusMuonGasGun.fcl Same as above, but using the muon gas gun. Very fast simulation.

beamtransport_gun.fcl Muons are not tracked around the ring. Instead, the position and momentum of the muon is calculated using the beam equations of motion and the muon appears in the ring just before it decays. A very accurate and fast simulation.

inflector_gun.fcl A very slow but accurate simulation of muons going through the inflector and around the ring.

Developer Workflow

The steps you follow to develop code is described here (eventually).

Writing Source Code

Warning: This section needs to be reviewed and cleaned up.

Your source code lives within a git project checked out to your development area's srcs directory. The project has a top level directory that contains the "top level" CMakeLists.txt file along with various subdirectories. Code with a common purpose should live in a particular subdirectory. You may mix headers (.h, .hh), implementation (.cc, .cpp), and configuration (.fcl) files all in the same subdirectory.

¹ For example, the gm2ringsim project would get checked out to srcs/gm2ringsim, which is the "top level" directory.

 2 Examine ${\tt gm2ringsim}$ for more examples.

6.1 Top level CMakeLists.txt file

The top level CMakeLists.txt file lives in your top level project directory (e.g. srcs/gm2ringsim/CMakeLists.txt). It has the main directives that tells CMake how to build your project.

Below is a representative top level CMakeLists.txt file.³ The mrb newProduct command will create a skeleton file for you.

art contains cmake modules that we use set(ART_VERSION \$ENV{ART_VERSION})

if(NOT ART_VERSION)
 message(FATAL_ERROR

```
# Ensure we are using a moden version of CMake
   CMAKE_MINIMUM_REQUIRED (VERSION 2.8)
   # Project name - use all lowercase
   PROJECT (gm2analyses)
   # Define Module search path
   set( CETBUILDTOOLS_VERSION $ENV{CETBUILDTOOLS_VERSION} )
   if( NOT CETBUILDTOOLS_VERSION )
     message ( FATAL_ERROR
10
            "ERROR: \square setup\square cetbuildtools\square to\square get\square the\square cmake\square modules" )
11
12
   13
                                             ${CMAKE_MODULE_PATH} )
14
```

- ³ There are five main parts of the file (roughly in order in the file)...
- Defining the project
- Loading CMake macros and setting the CMake environment
- Setting compiler options
- Specifying external packages that will be used
- Specifying subdirectories that contain a CMakeLists.txt file and, perhaps, code to build

```
"ERROR: usetupuartutougetutheucmakeumodules" )
  endif()
  set ( CMAKE_MODULE_PATH $ENV{ART_DIR}/Modules
                                             ${CMAKE_MODULE_PATH} )
25 # Import the necessary macros
26 include(CetCMakeEnv)
27 include (BuildPlugins)
28 include (ArtMake)
29 include (FindUpsGeant4)
31 # Configure the cmake environment
32 cet_cmake_env()
34 # Set compiler flags
  cet_set_compiler_flags( DIAGS VIGILANT WERROR
      EXTRA_FLAGS -pedantic
      EXTRA_CXX_FLAGS -std=c++11
37
  )
38
40 cet_report_compiler_flags()
42 # Set include and library search paths (the version numbers
_{
m 43} # are minimum - if actual version of product is below specified,
44 # will get error)
46 # Everyone should include these
47 find_ups_product(cetbuildtools v3_07_08)
48 find_ups_product(art v1_08_10)
49 find_ups_product(fhiclcpp v2_17_12)
50 find_ups_product(messagefacility v1_10_26)
52 # This project uses code from gm2ringsim,
# gm2dataproducts, and gm2geom
find_ups_product(gm2ringsim v1_00_00)
55 find_ups_product(gm2dataproducts v1_00_00)
56 find_ups_product(gm2geom v1_00_00)
58 # This project uses code from Root
59 find_ups_root(v5_34_12)
61 # Make sure we have gcc
62 cet_check_gcc()
# Macros for art_make and simple plugins (must go after
65 # find_ups lines)
66 include(ArtDictionary)
68 # Specify subdirectories to build
69 add_subdirectory( ups ) # Every project needs a ups subdirectory
70 add_subdirectory( DisplayDataProducts )
```

```
71 add subdirectory( calo )
  add_subdirectory( fcl )
  add_subdirectory( test )
  add_subdirectory( util )
   # Packaging facility - required for deployment
   include (UseCPack)
```

6.1.1 When you need to add/change a line in top level CMakeLists.txt

There are two situations for which you will have to alter the top level CMakeLists.txt file:

If you add, delete, or rename a subdirectory If you add a subdirectory, you must write a corresponding add_subdirectory(dirName) directive. 4 If you delete a directory, you must remove its corresponding add_subdirectory line. If you rename a directory, you must edit its corresponding add_subdirectory line to reflect the change. If you do not follow these steps, then some code may not build (without an error, so this mistake will be hard to find) or you may get an error when CMake tries to build a directory that no longer exists.

You use code from an external project If you use code from an external project, you may need to add a corresponding find_ups_product or similar line.⁵

Organizing Source Code

The build system we use is quite flexible and you can organize your code in many ways. You may be used to having all of your header files in an include directory with the .cc files in other directories. This artificial separation is unnecessary. You may group files together any way you like and may have header files and implementation files in the same directory. Typically, it is best to group files by topic or functionality.

6.3 Writing Modules

Modules are plugins to art that perform certain functions (analyzers, producers, filters, and output modules). See section 10 of the Art Work Book⁶ for more information. Only reminders will be given here.

You should use artmod to write the skeleton of the module. Do artmod --help-types to see the list of module types it will make. Then just run it, giving the name of the class you want including any namespace specification. For example,

⁴ The add subdirectory directory tells CMake to go into that subdirectory and build code there. If you don't have the add_subdirectory then CMake won't look in the subdirectory at all.

⁵ See section 6.8 for instructions.

```
artmod producer tracking: TrackFinder
artmod analyzer gm2analysis::CalorimeterDiags
```

Remember that you specify the class name, not the file name (so do not give _module in the name).

6.4 Writing Services

TODO

Writing Input Source Modules 6.5

TODO

6.6 Directory level CMakeLists.txt file

If your subdirectory (e.g. srcs/gm2analyses/strawTracker) has anything to build, has header files, or has further subdirectories, then it must have a CMakeLists.txt file (and a corresponding add_subdirectory line in the CMakeLists.txt from the directory above - see Sec. 6.1.1). If your subdirectory has code to build, then the directory CMakeLists.txt file needs to have

```
art_make(
```

A directory with no .cc or .cpp files has no code to build and so does not get an art_make line in the directory CMakeLists.txt file.

See the next section (Sec. 6.6.1) for arguments to the art_make. You should call art_make only once per CMakeLists.txt file.

If your subdirectory has header files, then those have to be copied to the release area when one runs mrb install. To do that, you need a line the directory CMakeLists.txt file with

```
install_headers( ) # No arguments
```

If your subdirectory has fcl files, then those need to be copied to the build area as well as the release area. There is some scripting involved to do that (put the following in the directory CMakeLists.txt file),

⁷ The directory level CMakeLists.txt file is different from the top level

```
1 # install all *.fcl files in this directory to the release area
file(GLOB fcl_files *.fcl)
  install( FILES ${fcl_files}
           DESTINATION ${product}/${version}/fcl )
  # Also install to the build area
  foreach(aFile ${fcl_files})
    get_filename_component( basename ${aFile} NAME )
    configure_file(
```

CMakeLists.txt file. The latter is in your project top level directory, like ${\tt srcs/gm2analyses}$. The former is in a subdirectory of that top level and is described in this section.

```
${aFile} ${CMAKE_BINARY_DIR}/${product}/fcl/${basename}
10
             COPYONLY )
11
   endforeach(aFile)
12
```

If your subdirectory has futher subdirectories with code to build, then you need an add_subdirectory(dirName) line for each subdirectory.

Arguments to art_make

You can find documentation for art make in its source code at \$ART_DIR/Modules/ArtMake.cmake. Basically, you need to specify what libraries to link against when you use external code. 8 If you don't use any external code, then you will have no arguments to art_make. It will tell CMake to build all regular source, modules, services, and input sources in the directory. If you do use external code, then you have four choices,

• If the source file using external code is a regular source (not a module, not a service, not an import source), then you need

```
art_make(
      LIB LIBRARIES
      library1
                  # if needed
      library2
)
```

• If the source file using the external code is a module source (e.g. analyze_my_hits_module.cpp) then you need

```
art_make(
             MODULE LIBRARIES
2
             library1
             library2
                          # if needed
         )
```

• If the source file using the external code is a service source (e.g. analyze_my_hits_service.cpp) then you need

```
art_make(
             SERVICE LIBRARIES
2
             library1
             library2
                         # if needed
         )
```

• If the source file using the external code is source code for an input

```
(e.g. midas_source.cpp) then you need
```

⁸ See Sec. 6.8 for how to tell if you are using external code.

```
art_make(
      SOURCE_LIBRARIES
      library1
      library2
                  # if needed
  )
```

If you have a mixture of sources in your directory, you can string the calls together. For example,⁹

```
art_make (
           LIB_LIBRARIES
2
               ${ROOT GPAD}
            MODULE_LIBRARIES
               gm2analyses_util
               gm2analyses_strawtracker_util
```

Note that it does not hurt for code to build against a library that it doesn't need. So if you have five modules and only one needs to link against a library, put that library in the MODULE LIBRARIES section. The one that needs it will link against it and the four that don't won't care.

Libraries produced from building

Every directory in your project that has code to build generates at least one library. 10 Say, for example, you have a directory called gm2analyses/calo. Regular sources (not modules, services, nor input sources) get compiled and the objects go into a library called libgm2analyses_calo.so (the name is the directory path with slashes replaced by underscores). Each module in the directory gets its own library. For example, if there is a module in that directory called Analyze_Calo_module.cc then that code will go into a library called libgm2analyses_calo_Analyze_Calo_module.so. A similar thing happens for services and input sources. Therefore, one directory of code may produce several libraries. The art_make directive in the directory CMakeLists.txt file tells the build system to build code and make the corresponding libraries.

6.8 Using External Code (Linking)

Your code is almost never self-contained, especially when writing within the Art framework. You may use functions and classes from external libraries, like Root and Geant4. You may use algorithms, data products, and other functionalities from other projects, like

⁹ In the example to the left, regular sources get linked against Root's ${\tt libGpad.so}$ (see Sec. 6.8.2) and modules get linked against code built in the srcs/gm2analyses/util and srcs/gm2analyses/strawtracker/util directories (see Secs. 6.8.4 and 6.8.5).

¹⁰ An important note, if your directory only has header files in it (should be a rare situation for code written by users), then no library will be produced (because there is no code to build - the header files are all included by other source code). You still need the directory level CMakeLists.txt file for the install_headers() directive, but do not do art_make. See Sec. 6.6.

gm2ringsim. You may use objects defined in other directories in your project. If you are writing an art module or service, you may use objects defined in the same directory, but in a different file from the module or service. All of these examples are "external code".

Art uses dynamic linking, which means that the art executable (ours is called gm2) has very little code in it. Instead, it loads all of the libraries it needs at runtime. The other style is static linking where the executable has embedded in it all of the libraries it needs. Dynamic linking, as the name suggests, allows for flexibility with one executable able to load a variety of different libraries decided upon at runtime with the configuration file. There is, however, overhead in dynamic loading typically experienced as slow start-up time of the program. Static linking produces an executable with all of the libraries built in - so there is little flexibility in terms of functionality. But the start up time is much faster. Static linking typically leads to many copies of executables for the different functionalities, resulting in duplication of libraries that are in common. For maximum flexibility and non-duplication of libraries, art loads everything dynamically.

HOW DO YOU KNOW WHEN YOU ARE USING EXTERNAL CODE? An easy indicator is when you have a #include for a header file. For each #include, you need to think and perhaps add a corresponding link directive in a CMakeLists.txt file. 11 If you forget to link to a library that you need, you will get a missing symbol error when you try to run. This section will explain how to figure out these situations and actions you need to take.

Includes for system headers and base art headers 6.8.1

System headers, like #include <string> do not require any special directives for linking. You get them for free.

Headers in art, fhiclopp, and messagefacility do not require anything in your directory level CMakeLists.txt file. The corresponding libraries are automatically loaded by the art executable. Your top level CMakeLists.txt file must contain the following lines, 12

```
cet_report_compiler_flags()
find_ups_product(art v1_08_10 )
find_ups_product(fhiclcpp v2_17_12)
find_ups_product(messagefacility v1_10_26)
. . .
```

¹¹ Remember the two types of CMakeLists.txt files: "top level" and "directory level". The former (see Sec. 6.1) is the potentially big file at the top level of your project. The latter (see Sec. 6.6) is the smaller file in the directory with your actual source code files.

¹² These lines add header file directories to the compiler include search path (e.g. without them, you will get a compilation error that header files cannot be found).

6.8.2 Includes for Root headers

Including a header from Root is a little unusual because you do not have to give a path in the include, e.g. #include "TCanvas.h" (not #include "root/TCanvas.h"). If you include a header from Root, you will also need to link to the corresponding Root library. First, in the top level CMakeLists.txt file, you must have, ¹³

```
cet_report_compiler_flags()
find_ups_root(v5_34_12)
```

¹³ That find_ups_root line adds the Root headers to the compiler include search path and creates CMake variables corresponding to each Root library.

If you look at the code for the find_ups_root CMake macro at \$CETBUILDTOOLS/Modules/FindUpsRoot.cmake you will see lines $\rm like, ^{14}$

```
find_library(ROOT_GLEW NAMES GLEW PATHS ${ROOTSYS}/lib
                                                  <sup>14</sup> These lines define the CMake
                  NO_DEFAULT_PATH)
                                                  variables that correspond to Root
find_library(ROOT_GPAD NAMES Gpad PATHS ${ROOTSYS}\hbrides. You use them in the direc-
                                                  tory level CMakeLists.txt file to tell
                  NO DEFAULT PATH)
NO DEFAULT PATH)
find_library(ROOT_GRAF3D NAMES Graf3d PATHS ${ROOTSYS}/lib
                  NO DEFAULT PATH)
```

To determine the Root library you need, look up the Root object in the Root documentation at http://root.cern.ch/drupal/content/ reference-guide (select the appropriate version of Root - usually the PRO version). Find the class name from the list and click on it. On the new page, on the very right hand side in a little greyed out box it will say the library that corresponds to that Root object. For example, if you #include "TCanvas.h" you need to link against the libGpad library. The CMake variable name will in general be the name of the library, all upper case, with the lib replaced by ROOT. So libGpad \rightarrow \${ROOT_GPAD}.

In your directory level CMakeLists.txt file, you will have the art_make directive. Add the appropriate CMake variable corresponding to the Root library you need. See Sec. 6.6.1 for where to put such items in the arguments. For example, ¹⁵

```
art_make (
   LIB_LIBRARIES
      ${ROOT_GPAD}
   MODULE_LIBRARIES
      ${ROOT_TREE}
      ${ROOT_TVMA}
```

¹⁵ In the example left, regular sources are linked against ${\tt libGpad.so}$ while modules are linked against libTree.so and libTVMA.so.

) 7

Includes for GEANT headers

To include a header file from Geant4, requires you to have Geant4/ in the header path, for example #include "Geant4/G4Track.hh". If you include such headers in your code, then you will also need to link against the Geant4 libraries. First, in your top level CMakeLists.txt file, you must have,

```
cet_report_compiler_flags()
2
    find_ups_geant4(v4_9_6_p02)
```

That line adds the Geant4 headers to the compiler include search path and creates the CMake variables \${G4_LIB_LIST} and \${XERCESLIB}. For any Geant4 header, just add those CMake variables to the art_make directive in your directory CMakeLists.txt file. See Sec. 6.6.1 for where to put such items in the arguments. For example,

srcs/gm2ringsim/calo/CMakeLists.txt has, in part, 16

```
art_make(
         LIB_LIBRARIES
              gm2geom_calo
              gm2geom_station
              artg4_material
              artg4_util
              ${XERCESCLIB}
              ${G4_LIB_LIST}
         SERVICE_LIBRARIES
              gm2ringsim_calo
10
           )
11
```

6.8.4 Includes for headers in the project

The **#include** directive should include the path to the header file, including the name of the project even if the header is in the same directory as the source, though you could just give the header file name. For example, if CaloHitSD.hh is in the gm2ringsim/calo directory, then CaloHitSD.cc, when it includes CaloHitSD.hh, can do either

```
#include "CaloHitSD.hh"
```

 $^{16}\,\mathrm{If}$ you are curious, you can see where $G4_LIB_LIST$ is defined in \$CETBUILDTOOLS_DIR/Modules/FindUpsGeant4.cmake. XERCESLIB goes with Geant.

```
or

#include "gm2ringsim/calo/CaloHitSD.hh"
```

The latter is preferred as it is clearer, but if you change the name of the directory, you must change the include as well.

If you have a regular source file and it includes a header that is present in the same directory, then you do not need to do anything to the CMakeLists.txt files. If you have a module, service, or input source file and it includes a header that is present in the same directory, then you need to link against the library for that directory. You do not need to add anything to the top level CMakeLists.txt file. To the directory CMakeLists.txt file, you must add the library. See Sec. 6.6.1 for where to put such items in the arguments. For example, srcs/gm2ringsim/calo/CMakeLists.txt has, in part, 17

```
art_make(

LIB_LIBRARIES

gm2geom_calo

gm2geom_station

gm2ringsim_station

artg4_material

artg4_util

s{XERCESCLIB}

s{G4_LIB_LIST}

SERVICE_LIBRARIES

gm2ringsim_calo

)
```

If any source file uses a header that is present in a different directory in your project, then you must link against that library. In the example above, code in the gm2ringsim/calo directory includes code from gm2ringsim/station, and hence gm2ringsim_station is present in the arguments of art_make.

An important exception to these instructions is if the directory with the header file contains **only** header files. In that case, that directory produces no libraries and you do not have to change the directory CMakeLists.txt file.

6.8.5 Includes for headers in other projects

If you have a source file (regular, module, service, or input source) that uses code from another project, then you need to do some work. An example here is code in gm2ringsim uses code from the gm2geom and artg4 projects. The #include needs the path to the header file including project name, directory name and header name. For example, #include "artg4/uti1/uti1.hh".

¹⁷ In the left example, services in that directory are linked against the library that gets created from the regular sources, namely libgm2ringsim_calo.so. You can predict the name of the library by taking the source directory (e.g. gm2ringsim/calo) and replacing the slashes by underscores.

In your top level CMakeLists.txt file, you need a find_ups_product line for the project specifying the project name and a minimum version number. See Sec.6.1 for an example.

In your directory CMakeLists.txt file, you need to list the library corresponding to the code you are using. See Sec. 6.6.1 for where to put such items in the art_make arguments. For example, srcs/gm2ringsim/calo/CMakeLists.txt has, in part,

```
art_make(
         LIB_LIBRARIES
2
              gm2geom_calo
              gm2geom_station
              artg4_material
              artg4_util
              ${XERCESCLIB}
              ${G4_LIB_LIST}
         SERVICE_LIBRARIES
              gm2ringsim_calo
10
           )
11
```

When the regular sources are built, they will be linked against code in gm2geom/calo, gm2geom/station, artg4/material, and artg4/util.

An important exception to these instructions is if the directory with the header file contains only header files. In that case, that directory produces no libraries and you do not have to change the directory CMakeLists.txt file. You still need to have the top level CMakeLists.txt file correct as described above.

Things You May Do in Your Code

This chapter contains some reminders of common things you do in Muon g-2 code.

7.1 Dealing with parameters

The constructor for your module or service has the parameter set as an argument. You can retrieve information from the parameter set and supply defaults if the parameter does not exist as in the example below.

7.2 Readling environment variables

```
#include <cstdlib>
//...
std::string value = std::getenv("PATH'');
```

The argument to std::getenv is a constant character array, not a std::string.

7.3 Throwing an exception

See http://mu2e.fnal.gov/public/hep/computing/exceptions.shtml.

```
#include "cetlib/exception.h"
// ...
if ( something ) {
```

```
throw cet::exception(CATEGORY) << "Message\n"
}</pre>
```

7.4 Finding a file

cetlib has a nice facility for searching for files in a path specification. See \$CETLIB_INC/cetlib/search_path.h.

It may be convenient to specify the search path in a FHICL parameter with the possibility of providing an environment variable. Here is some code that takes a search path through the parameter, but if the first character is a \$, it then gets the path through the specified environment variable.

```
gm2util::MetadataFromFile::MetadataFromFile(
             fhicl::ParameterSet const & p) :
       \mathtt{searchPath}_{\_}
                    (p.get < std::string > ("searchPath", ".")),
       fileName
                     (p.get < std::string > ("fileName")),
                     (p.get < std::string > ("keyName"))
       keyName_
  {
     // Let's parse the search path
     // If the first character is a dollar sign, then the
     // remaining is an environment variable
     if ( searchPath_.at(0) == "$" ) {
10
       std::string envVar = searchPath_.substr(1);
11
       char* envValue = std::getenv(envVar.c_str());
       if ( ! envValue ) {
13
         searchPath_ = ".";
14
         throw cet::exception("META_DATA_FROM_FILE") <<</pre>
          "Environment variable " << envVar << "uis not set";
       }
17
       searchPath_ = std::string(envValue);
     }
20
  }
21
```

Frequently Asked Questions

Some questions are answered here that didn't seem to fit in other sections.

Where is the art source code? The art source code¹ for a particular gm2 release is accessible in our release area for you to peruse. Set up the the release (see section 3) and look in \$ART_DIR/source/art.

¹ Never use the source code directory for an #include in your code. Instead, just use #include "art/whatever.h" and the build system will find it in \$ART_INC.

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